



MODEL 803



The Model 803 ROV Current Meter is a unique instrument, providing ROV pilots with relative water velocity data in real time. It may be fitted to ROVs to provide actual through the water speeds, or fitted to Tether Management Systems to give a measurement of local flow conditions. The selection of output options make interfacing easy, and data may be displayed using the software supplied. Available in both 500m acetal and 3000m titanium versions, the Model 803 is an extremely durable, reliable method of measuring current speeds in a wide variety of underwater vehicle applications.

Description

This instrument is the result of combining Valeport's proven current sensing technology with the knowledge and experience of some of the UK's leading ROV manufacturers and operators. The concept is simple - the Model 803 consists of a Valeport 2 axis electromagnetic flow sensor, with processing electronics capable of giving a variety of output formats for easy interface to almost any system.

The sensor should be mounted in clear flow on the ROV or TMS. When power is applied to the sensor, it measures the water velocity in 2 axes across the sensor surface. This data is updated at 1 second intervals, to provide X and Y axis flow information: the X axis is flow across the vehicle, and the Y axis is flow into the vehicle. This data can either be taken into a separate logging package, or displayed and logged to PC using the ROVLog Windows software provided.

As standard the Model 803 is supplied as a complete self-contained instrument, but can optionally be configured with separate sensor and electronics packages, or even as an OEM system. The Model 803 will appeal both to operators who wish to improve their existing vehicles, and to manufacturers who want to offer it as an additional parameter in the sensor package.

Physical

- Sensor:** 11.5cm discus EM sensor, made from polyurethane with titanium mounting.
- Housing:** Acetal for 500m depth rating
Titanium for 3000m depth rating.
- Dimensions:** 92mmØ x 350mm long
- Weight:** Acetal 0.5kg (in water)
Titanium 3.5kg (in water).
- Connector:** 8 way Subconn BH8M.

Performance

- Units:** Knots standard, option: m/s.
- Range:** ± 10kts (± 5m/s).
- Accuracy:** ± (0.02kts (0.01m/s) + 1% reading).
- Resolution:** 0.01kts (0.001m/s).

Output Formats

- Digital:** RS232 or RS485 (internally set). 19200 baud (default), 8 data bits, 1 stop bit, no parity bits.

String format: Kts: sxx.xx<tab>sy.yy<cr><lf>
M/s: sx.xxx<tab>sy.yyy<cr><lf>
Where: s= sign, + or -
xx.xx or x.xxx = speed on X axis
yy.yy or y.yyy = speed on Y axis

- Analogue:** -5 to +5v for each channel (0-5v or 0-10v (optional) also available).

Update rate: 1Hz default.

Power: 7 - 29vDC, 2W nominal.

Ordering

- 0803001** Model 803 ROV Current Meter in acetal housing. Supplied with pigtail / setup lead, operating manual and transit case
- 0803002** Model 803 ROV Current Meter in titanium housing. Supplied with pigtail / setup lead, operating manual and transit case
- 0803009** RS485 Communications adaptor for PC
- 0802025** Analogue output option (specify range)
- 0803006** Spare pigtail for Model 803