



MIDAS WLR - OPERATING MANUAL



Document ID MANUAL-1631736417-1 issue: 1.1
Date: July 2021

This confidential document was prepared by the staff of Valeport Limited, the Company, and is the property of the Company, which also owns the copyright therein. All rights conferred by the law of the copyright and by virtue of international copyright conventions are reserved to the Company. This document must not be copied, reprinted or reproduced in any material form, either wholly or in part, and the contents of this document, and any method or technique available there from, must not be disclosed to any other person whatsoever without the prior written consent of the Company.

© 2021 Valeport Ltd

Valeport Ltd
St Peter's Quay
Totnes TQ9 5EW
United Kingdom

Phone: +44 1803 869292
email: sales@valeport.co.uk
Web: www.valeport.co.uk

As part of our policy of continuous development, we reserve the right to alter, without prior notice, all specifications, designs, prices and conditions of supply for all our equipment

TABLE OF CONTENTS

1.	Introduction	1
2.	Specifications	2
2.1.	Sensor Specifications	2
2.1.1.	Pressure.....	2
2.1.2.	Temperature	2
2.2.	Mechanical Specifications.....	3
2.2.1.	Materials	3
2.2.2.	Connectors	3
2.3.	Performance Specifications	3
2.4.	Sample Lifetime Calculations.....	4
2.4.1.	Based on Memory	4
2.5.	A Note About Removable Memory.....	5
2.5.1.	Based on Batteries	6
2.6.	A Note About Rechargeable Cells	7
3.	Installation.....	8
3.1.	Communications With PC	8
3.2.	Deploying the MIDAS WLR.....	9
3.2.1.	Real Time Operation	9
3.2.2.	Self Recording Operation	9
3.2.3.	LED Flashing Sequence.....	9
3.3.	Recovery	10
4.	Maintenance	11
4.1.	Changing Batteries	11
4.2.	Seals	12
4.2.1.	O-Rings.....	12
4.2.2.	Anti-Extrusion Rings	13
5.	Wiring Information	14
5.1.	Switch Plug.....	14
5.2.	3m Y Lead (RS232)	14
5.3.	3m Switched Y Lead (RS485 & RS422).....	15

1. INTRODUCTION

This manual covers the specification, wiring details and basic maintenance procedures for the Valeport MIDAS WLR Seabed Tide Recorder. Full details of how to operate the instrument with the DataLog Express software supplied are given in a separate manual.

As standard, the MIDAS WLR system consists of the following components:

- Titanium or acetal housed instrument
- Stainless steel deployment cage
- 3m Y lead (interface to PC)
- Switching Plug
- Basic maintenance tools and spare o-rings
- DataLog Express Software
- Operating Manual
- Transit case

In addition, the following components may be supplied as optional extras:

- RS485 communications adaptor
- RS422 communications adaptor
- Bluetooth communications adaptor (19200 baud only)
- FSK modem communications adaptor (includes pcb in instrument)
- Various lengths & types of signal cable are also available

Note that instruments are often supplied (on request) with minor adjustments to the above list, such as a 5m Y lead instead of a 3m Y lead for example. Such variations will be detailed on the instrument packing list, and not in this manual.

Contact Information

If you have any questions about the operation of the instrument, which are not answered by this manual, please contact your supplier if appropriate, or contact Valeport Ltd directly at the address given at the front of this manual.

2. SPECIFICATIONS

2.1. Sensor Specifications

The unit is fitted with the following sensors:

2.1.1. Pressure

Type:	Temperature Compensated Piezo-Resistive Sensor
Range:	Various available, 10Bar (approx 100m water depth) to 600Bar (approx 6000m water depth)
Precision:	$\pm 0.01\%$ Full scale (± 1 cm for 10Bar sensor, ± 0.6 m for 600Bar)
Resolution:	0.001% Full scale (1mm for 10Bar sensor, 6cm for 600Bar)

2.1.2. Temperature

Type:	Fast response PRT
Range:	-5 to +35°C
Accuracy:	$\pm 0.005^\circ\text{C}$
Resolution:	0.001°C

2.2. Mechanical Specifications

2.2.1. Materials

Housing:	Titanium or acetal, as ordered
Exceptions:	Temperature sensor is titanium.
Cage:	Stainless steel (316 grade) with polypropylene clamping brackets
Dimensions:	Instrument - 88mm Ø, 550mm long (including connector) Cage – 750mm long x 140mm x 120mm
Weight (in cage):	11.5kg (air), 8.5kg (water).
Depth Rating:	Acetal 500m (unless smaller pressure sensor fitted) Titanium 6000m (unless smaller pressure sensor fitted)

2.2.2. Connectors

Instrument:	10 pin female SubConn bulkhead type (MCBH10F) with lock ring.
Comms Cable:	Valeport 3m Y lead. 10 pin male SubConn line type (MCIL10M) to instrument, 2 x 4mm bunch pins to external power, 9 pin female D type to PC.
Switching Plug:	10 pin male SubConn line type (MCIL10M), with lock ring. Note that the switch cap contains wiring links to activate the instrument

It is not a dummy plug.

2.3. Performance Specifications

Memory:	16Mb solid state memory (upgradeable in 16Mb steps to 64Mb)
Internal Power:	8 x 1.5v alkaline C cells. The unit will accept 8 x 3.6v Lithium C cells with no alterations required. <u>Do not mix battery types.</u>
External Power:	Between 9 and 30v DC.
Current Drain:	25mA at 12v when running, and 0.25mA when in sleep mode.
Sampling Rate:	1, 2, 4 or 8Hz (synchronised)
Data Output:	RS232, RS485 or RS422, depending on pin selection. Baud rate is user selectable from 2400 to 460800

2.4. Sample Lifetime Calculations

2.4.1. Based on Memory

Lifetime based on memory is simple to calculate. Pressure values use 4 bytes of memory per sample, and temperature uses 2 bytes. Therefore total memory used per record is $4 + 2 = 6$ bytes.

The 16 Mbyte memory actually contains 16,777,216 bytes. Allowing a small amount of memory usage for header files, the memory will store over 2.7 million records.

The length of time that this memory will last for obviously depends on sampling scenario. Here are two examples:

2.4.1.1. Continuous data sampling, 8Hz:

Memory used per second is 8×6 bytes = **48 bytes**

Total memory fitted is **16,777,216 bytes**

Seconds before memory full is $16,777,216 / 48 =$ (approx) **349,500 seconds**

This is equivalent to **97 hours**

This period could be doubled by sampling at 4Hz

2.4.1.2. Burst sampling, 4Hz, sampling 1 minute in every 10, recording all data points:

Memory used per burst is $6 \text{ bytes} \times 4\text{Hz} \times 60 \text{ seconds} =$ **1440 bytes**

The memory will therefore be full after $16,777,216 / 1440$ bursts = **11650 bursts**

At a 10 minute cycle time, this is **116500 minutes**, which is equivalent to **80 days**

2.4.1.3. Burst sampling, 4Hz, sampling 1 minute in every 10, recording averaged data:

Memory used per burst is 6 bytes.

The memory will therefore be full after $16,777,216 / 6$ bursts = **11650 bursts**

At a 10 minute cycle time, this is **2796202 minutes**, which is equivalent to **1941 days**

2.5. A Note About Removable Memory

We are sometimes asked whether we offer these devices with removable memory. The answer is no we don't, but there are sound reasons for this. It is natural to think that since removable memory cards are now the norm in consumer electronics, they must be "state of the art" and therefore desirable in all applications, but this is not necessarily the case.

- An essential feature of an underwater instrument is that it is water-tight; this is achieved by using various seals on the mechanical parts of the device. Every time that one of these seals is broken and remade, it introduces a small risk that the seal is not correctly made, and the instrument could leak. The fewer times that the device has to be opened, the better – you certainly wouldn't want to do it after every profile to get the memory card out.
- All memory cards are susceptible to ESD shock (static electricity) while being handled. We take the view that the value of your data means it shouldn't be exposed to the possibility of this risk, which could result in loss of all data on the card.
- Memory cards are not particularly efficient at storing data – they will only accept minimum sized lumps of data at a time. This may be perfect for a camera where you instantly generate a few Mbytes, not so for an application where you only want to store a few bytes of data at a time.
- From a practical point of view, the time taken to connect a cable and extract the data to PC is actually typically much less than the time to open the device, remove the memory, replace the memory, and close the device up again.
- The implementation of removable memory is not technically difficult, but we believe that the disadvantages currently outweigh any possible advantages in this product and its applications. However, should circumstances change it will of course be considered for future product enhancements.

2.5.1. Based on Batteries

The MIDAS WLR will function with a voltage supply of between 9 and 30vDC. The voltage output of the 8 x C cell battery pack will vary according to the type of cell fitted. The most likely cells to be used will be standard alkaline type (1.5v each) or Lithium cells (3.6v each), giving a 12v nominal output for alkaline cells, or 28.8v nominal for Lithium cells. The following calculations are based on the same sampling scenarios as the memory calculations, using figures for a 12v alkaline battery pack. Each example also gives a figure for a Lithium battery pack, calculated from a basic ratio of alkaline to Lithium performance.

In all examples, it is taken that an 8 C cell alkaline battery pack will have a nominal capacity of 7.8Ah, and will be 75% efficient (total available charge, 5.85Ah), and that an 8 C cell Lithium pack will have a nominal capacity of 7.2Ah, and will be 95% efficient (total available charge, 6.8Ah).

2.5.1.1. Continuous data sampling, 8Hz:

At 12v, the instrument draws **25mA** when sampling.

Total charge available is **5850mAh**.

Number of hours available is therefore 5850mAh / 25mA = **234 hours**.

This is equivalent to just less than **10 days**.

For Lithium cells, a similar calculation gives around **23 days**.

2.5.1.2. Burst sampling, 4Hz, sampling for 1 minute every 10 minutes:

At 12v, instrument draws **25mA** when sampling, plus **21mA** for 5 seconds at the start of each burst. It draws **0.04mA** when in sleep mode between bursts.

In this scenario then, the instrument will draw 25mA for 60 seconds, then 21mA for 5 seconds, and then 0.04mA for 535 seconds. On average, it will draw:

$$\frac{(25 \times 60) + (21 \times 5) + (0.04 \times 535)}{(60 + 5 + 535)} = 2.71\text{mA}$$

Total charge available is **5850mAh**.

Number of hours available is therefore 5850mAh / 2.71mA = **2158 hours**.

This is equivalent to approx **90 days**.

For Lithium cells, a similar calculation gives approx **215 days**.

The above examples are intended as guides only. Valeport accepts no responsibility for variation in actual performance

performance of individual battery cells is not always consistent.

2.6. A Note About Rechargeable Cells

We are often asked if rechargeable cells can be used. Yes, it is possible to use rechargeable cells, but we do not recommend it:

- Firstly, the cells cannot be recharged in-situ due to the possibility of the cells giving out gas inside a sealed instrument, effectively turning it into an explosive device. Whilst this risk is small, it does exist and therefore must be considered. The risk could be overcome by adding an air vent to the housing, but this could compromise the water-tight nature of the housing. Better to remove the risk altogether.
- Secondly, the most commonly used rechargeable cells are NiCad type. These only operate at around 1.2v maximum and have about 25% of the capacity of an alkaline cell; they therefore give greatly reduced operating times.
- Modern Li-ion or NiMH cells are more efficient than NiCad cells, but do not yet compare with alkaline cells. They are also considerably more expensive.

3. INSTALLATION

The standard system is supplied in an ABS transit case, together with any communications adaptors ordered. Any additional lengths of signal cable are packed separately.

3.1. Communications With PC

The MIDAS WLR can be set up and interrogated using the DataLog Express software supplied. Please refer to the separate manual for details of how to use the software.

To connect the instrument directly to a PC for RS232 communications, use the 3m Y lead supplied. This lead is fitted with a 10 pin SubConn type connector, which should be plugged directly into the connector on the top of the housing (or to a length of signal cable). The lead also features 2 x 4mm bunch pins for application of external power if required and a 9 way D type connector which should plug directly into a spare communications port on the back of the PC.

If non-RS232 communications are to be used, via the optional RS485, RS422 or FSK methods, then the appropriate adaptor should be used. Each adaptor is supplied with an alternative Y lead, which should be connected as follows:

Comms Method	Adaptor Part No.	Connections
RS485	0400029	Connect 15 pin D type and 4mm plugs from y lead into adaptor. Connect 9 pin D type from adaptor to PC, and 4mm plugs from adaptor to external power, as indicated on adaptor housing
RS422	0400030	Connect 15 pin D type and 4mm plugs from y lead into adaptor. Connect 9 pin D type from adaptor to pc, and 4mm plugs from adaptor to external power, as indicated on adaptor housing.
FSK	0400005	Connect 4mm plugs from y lead into adaptor, leaving D types unconnected (FSK uses power and signal on just two wires). Connect 9 pin D type from adaptor to PC, and 4mm plugs from adaptor to external power, as indicated on adaptor

3.2. Deploying the MIDAS WLR

All parts of the standard system (with the exception of the top part of the 3m Y lead) are designed for immersion. All communications adaptors (RS485, RS422, FSK) are splash proof, but should be sited in a dry place, as close to the PC as possible.

The MIDAS WLR is supplied with a stainless-steel protective cage, but care should still be taken not to damage the instrument. For profiling work, the recommended deployment method is to suspend the instrument using the stainless-steel wire strop fixed to the top of the cage. For fixed deployments, the user may wish to remove the cage, and use the grooves in the instrument housing as clamping points.

3.2.1. Real Time Operation

For real time data output, connect the signal cable to the 10 pin SubConn connector on the instrument. All Valeport signal cables include a suspension point for strain relief, and a similar arrangement is recommended for other cable types. Connect the top end of the cable to a PC using the appropriate method as described above.

3.2.2. Self Recording Operation

For self-recording only deployments, the instrument is switched on by insertion of the SubConn style switch plug. This plug must be inserted for the unit to operate.

Note that the switch plug is NOT just a dummy plug; it contains links between some of the pins as described in Section 5, which are used to turn the instrument on.

3.2.3. LED Flashing Sequence

The MIDAS WLR is fitted with an LED visible through a polycarbonate window in the battery pack. The LED will flash as detailed below to indicate various states.

Continuous ON for 15 seconds	Occurs when the Switch Plug or cable is connected, indicating that instrument is on and awaiting communication
1Hz Continual Flashing	Insufficient Power. Change internal batteries, or completely remove external power, and apply higher voltage
Continuous ON for 2 seconds	Indicates the start of Burst Sampling pattern
5 Rapid Flashes	Indicates the end of Burst Sampling pattern. The duration of the burst may be calculated as the time between the start and stop LED sequences, <u>less 5 seconds</u> .

3.3. Recovery

On recovery, data can be extracted to PC via the 3m Y lead. This procedure is covered in the separate software manual for DataLog Express.

To prolong the lifetime of the instrument the following procedures should be carried out once the instrument has been recovered:

- Remove any significant growth from the instrument. A high pressure water jet or stiff (not metal) brush is suitable – a hard toothbrush is ideal.
- Remove any significant growth from the pressure sensor port. Take care not to introduce any sharp objects onto the sensor face – this may result in sensor damage.
- Check instrument for signs of damage.
- Rinse the instrument in fresh water
- Dry the instrument if possible, paying particular attention to the sensors and connector.
- Repack the instrument in the transit case provided.

4. MAINTENANCE

The MIDAS WLR is completely solid state, and therefore requires very little maintenance. Other than keeping the instrument relatively clean (as described in Section 3.3, Recovery), the only procedure that the customer will be required to carry out on a regular basis is to change the batteries. This Chapter also covers details of the O-rings that are fitted to the instrument, and which should be checked periodically for damage and replaced if necessary.

4.1. Changing Batteries

The MIDAS WLR accepts 8 x C cells, of either 1.5v alkaline or 3.6v Lithium type. These cells are arranged in series, so the output voltage is 12v (alkaline) or 28.8v (Lithium). Some example scenarios for lifetime of these batteries are given in Chapter 2.4.2

The batteries are located in a holder in the top of the instrument, and should be accessed by removing the connector bulkhead.

(This step may be omitted)

For easier access, remove the instrument from the protective cage by loosening the M10 nuts on the polypropylene clamps. Gently lever these clamps apart, using a screwdriver if necessary.



Slide the instrument out of the cage, in either direction.



1. Remove the 3 M5 x 20 socket cap screws in the connector bulkhead, using the Allen key provided.
2. Without twisting or putting undue stress on the SubConn connector slide the bulkhead and attached battery pack out of the main housing. A slot between the tube and the bulkhead allows levering with a screwdriver if necessary. Take care not to scratch the bore of the tube.
3. A lead connects the battery pack to the electronics inside the tube. This may be disconnected at the battery pack if required, for ease.
4. Replace the batteries.



5. Check the condition of the bore seal o-rings, and apply a light coating of silicon grease. Ensure that both they and the anti-extrusion rings sit in the groove correctly, and are free from damage. Replace them if necessary (refer to Section 4.2).
6. Reattach the connector to the electronics if necessary, and gently slide the battery pack back into the tube, ensuring that the fixing holes are correctly aligned. Again, take care not to scratch the bore.
7. Replace the 3 x M5 screws, using a small amount of copper grease (supplied). Do not force the screws, just tighten firmly.
8. Finally, slide the instrument back into the protective cage. Note that the clamping brackets are offset, and that the sensor end of the instrument should lie at the long end of the cage.

4.2. Seals

The MIDAS WLR is kept watertight by using O-ring seals and anti-extrusion rings. Double O-ring seals are used at each end of the housing, although the customer should have no reason to open any seal other than that at the battery end.

A set of spare O-rings is included with the equipment. If an O-ring needs replacing, be sure to use the correct size. If obtaining further spare O-rings from an alternative source, be sure to obtain the correct material (signified by the last 4 digits of the O-ring code number).

O-ring size: 200-143-4470

Anti-extrusion ring size: 143 (titanium housing only)

4.2.1. O-Rings

To help preserve the watertight nature of the equipment, please observe the following guidelines:

- Ensure that all O-rings are free from cuts, abrasions or perishing.
- Ensure that all-O-rings are free from dirt, grit, sand, hair and other foreign objects.
- With titanium housings, ensure that an anti-extrusion ring is fitted on the low pressure side of each O-ring (see Section 4.4.2)
- Whenever an O-ring seal is opened (e.g. when changing batteries), ensure that a light coating of silicon grease is applied to the O-ring before the seal is closed.
- Ensure that all O-ring protected seals are tightened.

4.2.2. Anti-Extrusion Rings

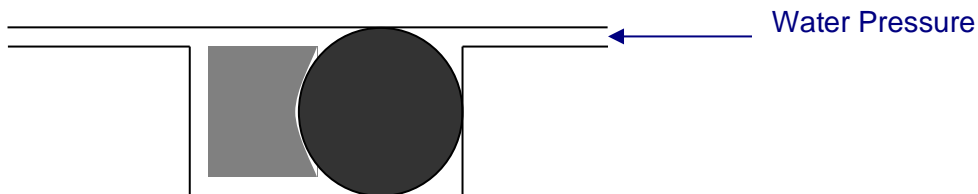
It is common Valeport practice to fit Anti-Extrusion Rings, also known as AE Rings or Backing Rings, to O-ring seals on deep water instrumentation.

The function of an AE Ring is to prevent the O-ring from being squeezed out of its groove under high pressure. Whilst this may not immediately cause a leak, it can damage the O-ring to the extent that it will not properly seal on subsequent deployments.

Where an AE ring is fitted, Valeport favour a single solid ring type made from nitrile rubber. These are black or dark grey in appearance, and are distinguishable from the O-ring itself by having a square cross-section, with a single concave surface, as illustrated:



These rings should be fitted into the O-ring groove on the “dry”, or low-pressure side of the O-ring, with the concave surface adjacent to the O-ring itself:



It is particularly important to note that in order to fit these rings, they must be stretched slightly to pass over the instrument body. This stretch does not immediately recover, with the result that the AE ring may not sit snugly in the groove at first. Fitting the tube to the instrument at this point may result in the AE ring riding out of the groove, and preventing a proper seal. The instrument may then leak.

Once an AE ring has been fitted, please leave a minimum of 30 minutes for it to recover its shape before fitting the tube.

5. WIRING INFORMATION

5.1. Switch Plug

10 Way Male SubConn	Function
1	Link to Pin 10
2	NC
3	NC
4	NC
5	NC
6	NC
7	NC
8	NC
9	NC
10	Link to Pin 1

5.2. 3m Y Lead (RS232)

10 Way Male SubConn	1m Power Cable	4mm Banana Plugs	9 Way D Type	Function
1	BLUE	BLACK		Power Ground
2	BROWN	RED		Power +V
3				
4				
5				
6				
7			2	RS232 Tx (To PC)
8			3	RS232 Rx (From PC)
9			5 (link to 1,6,8,9) SHELL	RS232 Ground
10				Internal Battery Enable Link to RS232 Ground

5.3. 3m Switched Y Lead (RS485 & RS422)

10 Way Male SubConn	SWITCH BOX	1m White Cable	4mm Banana Plugs	15 Way D Type	9 Way D Type	Function
1		BLUE	BLACK			Power Ground
2		BROWN	RED			Power +V
3				9		RS422 TxA
4				10		RS422 TxB
5				11		RS422 RxA
6				12		RS422 RxB
7					2	RS232 Tx (To PC)
8					3	RS232 Rx (From PC)
9				5	5 (link to 1,6,8,9)	RS232 Ground
			SHELL	SHELL		
10					Internal Battery Enable	